

A Two Fluid Model for Two-Phase Flows with Free Interface

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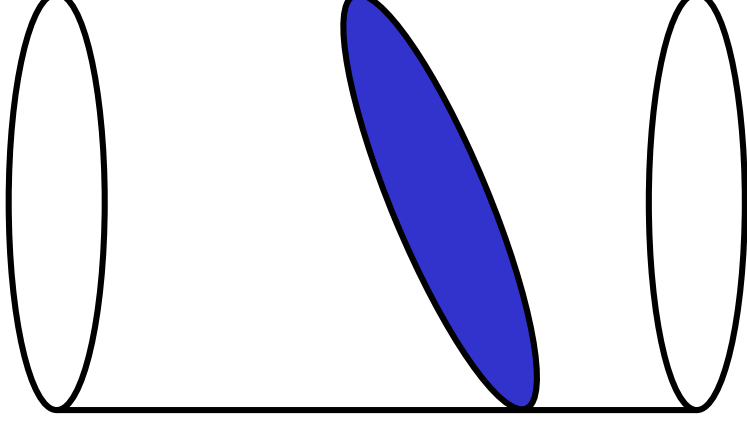
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The ONERA logo consists of the word "ONERA" in a serif font, underlined. Below the underline is a blue curved line that starts under the 'O', goes up and over the 'N', and then curves down under the 'A'.

Context and Applications

Fluids behaviour in tanks :

- Sloshing effects due to transverse accelerations
- Surface tension effects due to possible gravity reduction and interface curvature
- Thermal effects due to external heat fluxes



Main Features of our approach

- Eulerian method on a fixed grid, with no interface reconstruction or interface tracking, existence of an artificial mixture zone
 - need of a mixture closure law leading to a well-posed problem (hyperbolic system, thermodynamic consistency)
 - need of a low diffusive numerical scheme
- able to deal with a wide range of applications relative to fluid behaviour in a launcher tank (including coupling between thermal and hydrodynamic effects)
 - compressible two fluid model, eventually with “pseudo” sound speeds, to overcome low Mach number difficulties

Modeling Hypothesis

- Gas of density ρ_g , liquid of density ρ_ℓ , supposed to be compressible and inviscid
- no thermal effects : linearized EOS

$$p_g(\rho_g) = p_0 + c_g^2(\rho_g - \rho_{g0}), \quad p_\ell(\rho_\ell) = p_0 + c_\ell^2(\rho_\ell - \rho_{\ell0})$$

- the two fluid “fictitiously” coexist everywhere, presence characterised by volume fraction α_g , α_ℓ : $\alpha_g + \alpha_\ell = 1$
- only one velocity field

The Equilibrium Model

$$\underbrace{\left. \begin{aligned}
 \frac{\partial \tilde{p}_g}{\partial t} + \frac{\partial}{\partial x} \tilde{p}_g u + \frac{\partial}{\partial y} \tilde{p}_g v &= 0 \\
 \frac{\partial \tilde{p}_\ell}{\partial t} + \frac{\partial}{\partial x} \tilde{p}_\ell u + \frac{\partial}{\partial y} \tilde{p}_\ell v &= 0 \\
 \frac{\partial}{\partial t} \rho u + \frac{\partial}{\partial x} (\rho u^2 + P) + \frac{\partial}{\partial y} \rho uv &= \mathbf{F}_x \\
 \frac{\partial}{\partial t} \rho v + \frac{\partial}{\partial x} \rho uv + \frac{\partial}{\partial y} (\rho v^2 + P) &= \mathbf{F}_y
 \end{aligned} \right\} (E)$$

with: $\tilde{p}_g = \alpha \rho_g$, $\tilde{p}_\ell = (1 - \alpha) \rho_\ell$, $\rho = \tilde{p}_g + \tilde{p}_\ell$

The Equilibrium Model : closure laws

mixture pressure

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Mixture pressure P :

$$P(\tilde{p}_g, \tilde{p}_\ell) = \alpha^* p_g \left(\frac{\tilde{p}_g}{\alpha^*} \right) + (1 - \alpha^*) p_\ell \left(\frac{\tilde{p}_\ell}{1 - \alpha^*} \right)$$

where :

$$\alpha^* = \alpha^*(\tilde{p}_g, \tilde{p}_\ell)$$

is the equilibrium gas volume fraction insuring :

$$p_g \left(\frac{\tilde{p}_g}{\alpha^*} \right) = p_\ell \left(\frac{\tilde{p}_\ell}{1 - \alpha^*} \right)$$

The Equilibrium Model : closure laws

source terms

Source terms \mathbf{F} :

- acceleration in the local reference frame
(gravity + transverse acceleration)
- surface tension, CSF way : $\mathbf{F}_c = \sigma \kappa \nabla \alpha$
(Brackbill *et al*, JCP 1992)
- σ the surface tension coefficient
 $\kappa \nabla \alpha = -\nabla \cdot \left(\frac{\nabla \alpha}{\|\nabla \alpha\|} \right) \nabla \alpha$

The Equilibrium Model : closure laws

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“conservative” capillary force

joint work with D. Jamet, CEA

$$\text{The capillary force : } \mathbf{F}_c = -\sigma \nabla \cdot \left(\frac{\nabla \alpha}{\|\nabla \alpha\|} \nabla \alpha \right)$$

$$\text{also reads : } \mathbf{F}_c = -\sigma \nabla \cdot \left(\frac{\nabla \alpha}{\|\nabla \alpha\|} \otimes \nabla \alpha \right) + \sigma \nabla (\|\nabla \alpha\|)$$

→ yields a completely conservative formulation of momentum equation

→ numerically, $\nabla \alpha$ needs only to be computed at the faces center

The Equilibrium Model :

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mathematical properties (without surface tension)

- The mixture pressure law leads to an **hyperbolic** system with mixture sound speed c_* such that :

$$\rho c_*^2 = \tilde{\rho}_g c_g^2 \left(1 + \frac{K}{\alpha} \right) + \tilde{\rho}_\ell c_\ell^2 \left(1 - \frac{K}{1-\alpha} \right) \quad \text{with } K = - \left(\tilde{\rho}_g \frac{\partial \alpha^*}{\partial \tilde{\rho}_g} + \tilde{\rho}_\ell \frac{\partial \alpha^*}{\partial \tilde{\rho}_\ell} \right)$$

- Existence of a **Lax entropy** $F^*(\tilde{\rho}_g, \tilde{\rho}_\ell, \rho u) = F(\alpha^*, \tilde{\rho}_g, \tilde{\rho}_\ell, \rho u)$ with :

$$F(\alpha, \tilde{\rho}_g, \tilde{\rho}_\ell, \rho u) = \underbrace{\tilde{\rho}_g \int \frac{p_g}{2} d\rho_g + \tilde{\rho}_\ell \int \frac{p_\ell}{2} d\rho_\ell}_{\text{free energy}} + \underbrace{\frac{1}{2} \rho u^2}_{\text{kinetic energy}}$$

- Difficulties with the explicit solution of the Riemann problem due to the complexity of the mixture pressure law
→ **Relaxation model** (in the spirit of Coquel & Perthame, SIAM 1998)

$$(R_\varepsilon) \left\{ \begin{array}{l} \frac{\partial \alpha}{\partial t} + u \frac{\partial \alpha}{\partial x} + v \frac{\partial \alpha}{\partial y} = \frac{p_g - p_\ell}{\varepsilon}, \quad (0 < \varepsilon \ll 1) \\ \frac{\partial w}{\partial t} + \frac{\partial F}{\partial x} + \frac{\partial G}{\partial y} = S \end{array} \right.$$

$$\text{with } P(\alpha, \tilde{p}_g, \tilde{p}_\ell) = \alpha p_g \left(\frac{\tilde{p}_g}{\alpha} \right) + (1 - \alpha) p_\ell \left(\frac{\tilde{p}_\ell}{1 - \alpha} \right)$$

similar models in :

- Saurel & Abgrall (JCP 1999), Saurel & Lemetayer (JFM 2001)
- Dellacherie & Rency (preprint 2001)

Remark : the relaxation source term is linked to F by :

$$\frac{p_g - p_\ell}{\varepsilon} = - \frac{1}{\varepsilon} \frac{\partial F}{\partial \alpha} = - \frac{1}{2\varepsilon} \left(\frac{\partial F}{\partial \alpha_g} - \frac{\partial F}{\partial \alpha_\ell} \right) \quad \text{thermodynamic potential}$$

The Relaxation Model :

mathematical properties (without surface tension)

- Also hyperbolic with mixture sound speed c such that :

$$\rho c^2 = \tilde{\rho}_g c_g^2 + \tilde{\rho}_l c_l^2$$

and verifying the **sub-characteristic condition** :

$$c_*^2 \leq c^2$$

- **good mathematical frame for relaxation**
a Chapman-Enskog like expansion of the relaxation model can formally be derived (as in Coquel & Perthame, SIAM 1998)
- F is an entropy, **compatible with the relaxation source term** :
the relaxation source term contributes to the decrease in entropy

Numerical Method

- Finite Volume method :
 - RK2 in time (2nd order)
 - Godunov-MUSCL in space (2nd order)
- Each RK2 stage divided in two parts
 - hyperbolic step (**exact Riemann solver**)
 - pressure relaxation step

Numerical Method :

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hyperbolic step

$$\begin{cases} \frac{\partial \rho \alpha}{\partial t} + \frac{\partial \rho \alpha u}{\partial x} + \frac{\partial \rho \alpha v}{\partial y} = 0 \\ \frac{\partial w}{\partial t} + \frac{\partial F}{\partial x} + \frac{\partial G}{\partial y} = S \end{cases}$$

Given α^n and w^n , we solve :

$$\text{by } \begin{pmatrix} \rho \alpha \\ w \end{pmatrix}_{ij}^{n*} = \begin{pmatrix} \rho \alpha \\ w \end{pmatrix}_{ij}^n - \Delta t \left(\frac{f_{i+1/2} - f_{i-1/2}}{\Delta x} + \frac{g_{j+1/2} - g_{j-1/2}}{\Delta y} \right) + \Delta t S_{ij}$$

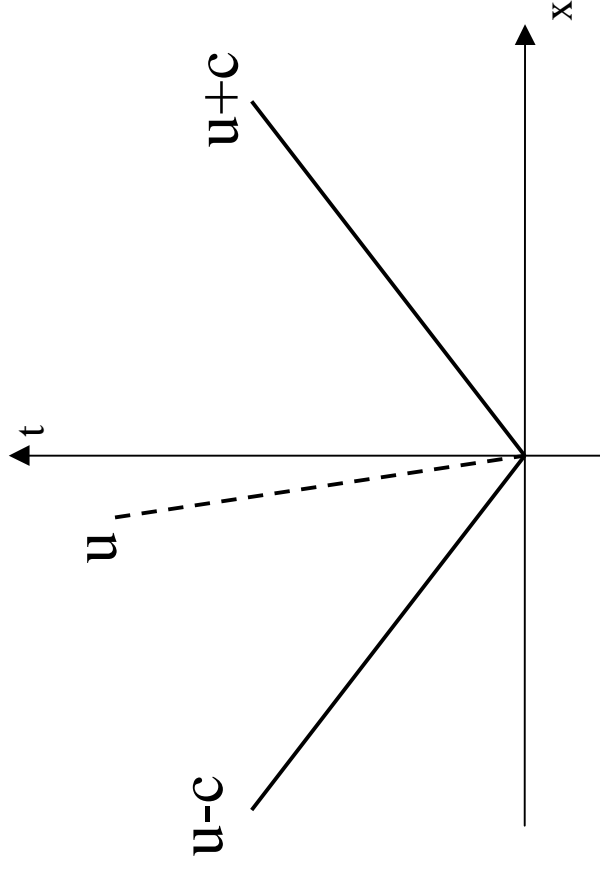
to obtain intermediate state $(\alpha, w)^{n*}$

Δt is fixed by a CFL condition

Numerical Method : hyperbolic step numerical scheme

Numerical flux functions f and g based on exact resolution of the associated Riemann problem :

Godunov Scheme



	u-c	u	u+c
Nature	shock or rarefaction	contact discontinuity	shock or rarefaction

Numerical Method : pressure relaxation step

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Given $(\alpha, w)^{n*}$, we solve with $\varepsilon \rightarrow 0$:

$$\left\{ \begin{array}{l} \frac{\partial \alpha}{\partial \tau} = \frac{P_g - P_\ell}{\varepsilon} \\ \frac{\partial w}{\partial \tau} = 0 \end{array} \right. \quad \text{only } \alpha \text{ change}$$

to obtain α^{n+1} and w^{n+1} :

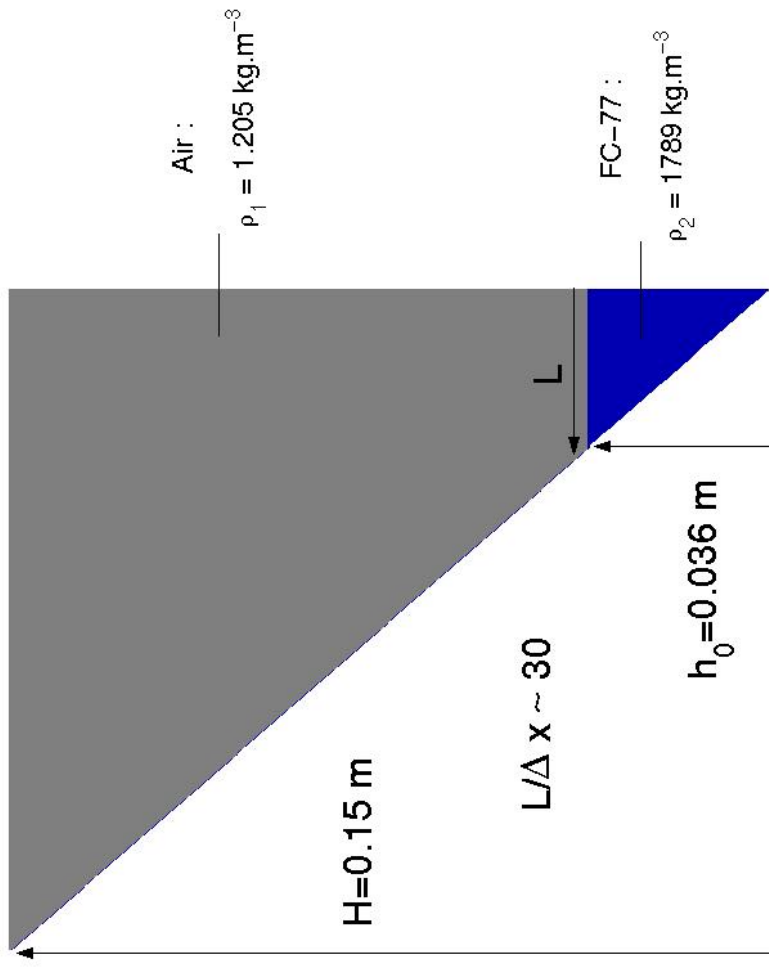
$$\left\{ \begin{array}{l} \alpha^{n+1} = \alpha^* (\tilde{\rho}_1^{n*}, \tilde{\rho}_2^{n*}) \\ w^{n+1} = w^{n*} \end{array} \right.$$

**no numerical scheme is needed for the
volume fraction with this approach**

Remark : α^* can be explicitly computed
for linearized EOS

Numerical Results : Sloshing in a 2D wedge

high Froude number, high Bond number

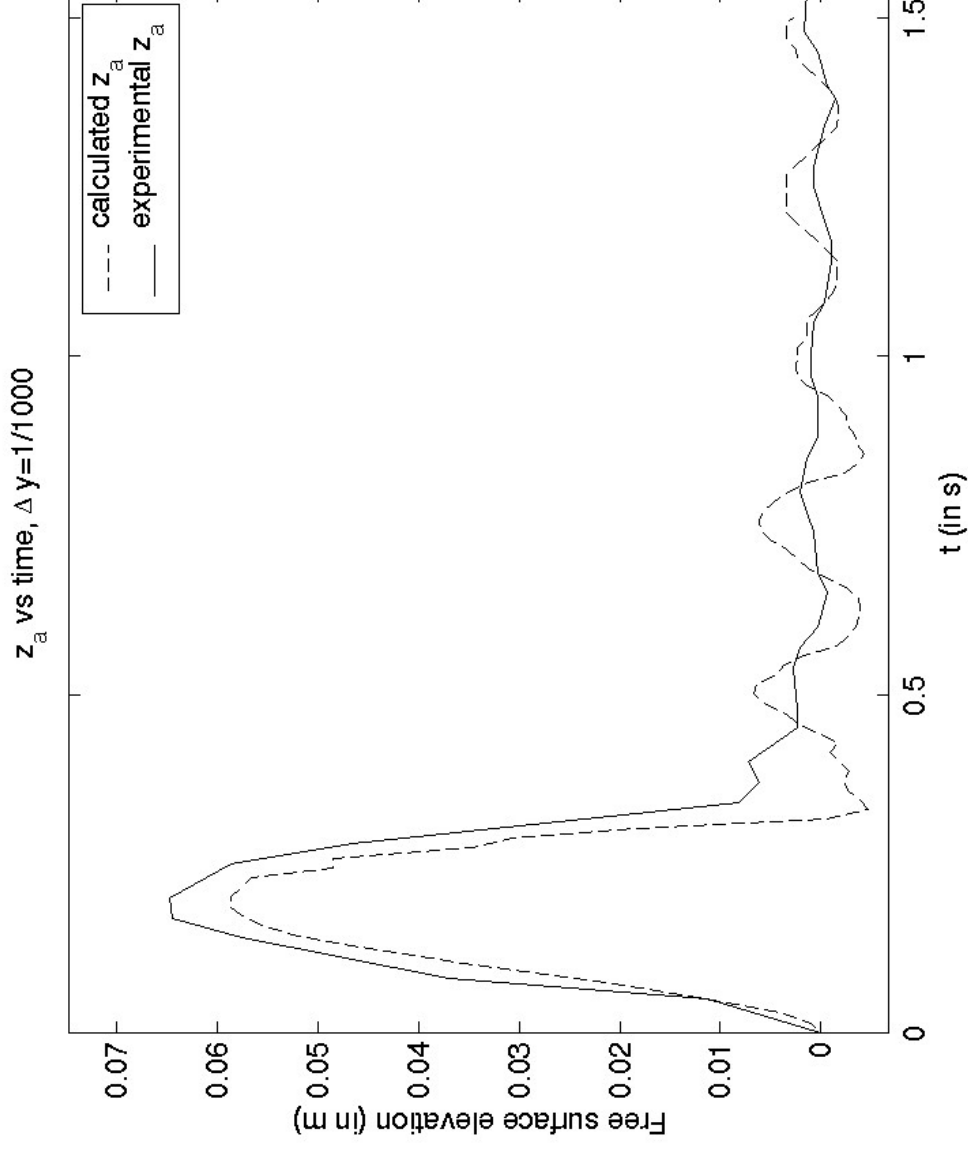


$$a_x = 9.81 \text{ m.s}^{-2} \text{ during } \Delta t = 0.1 \text{ s}$$

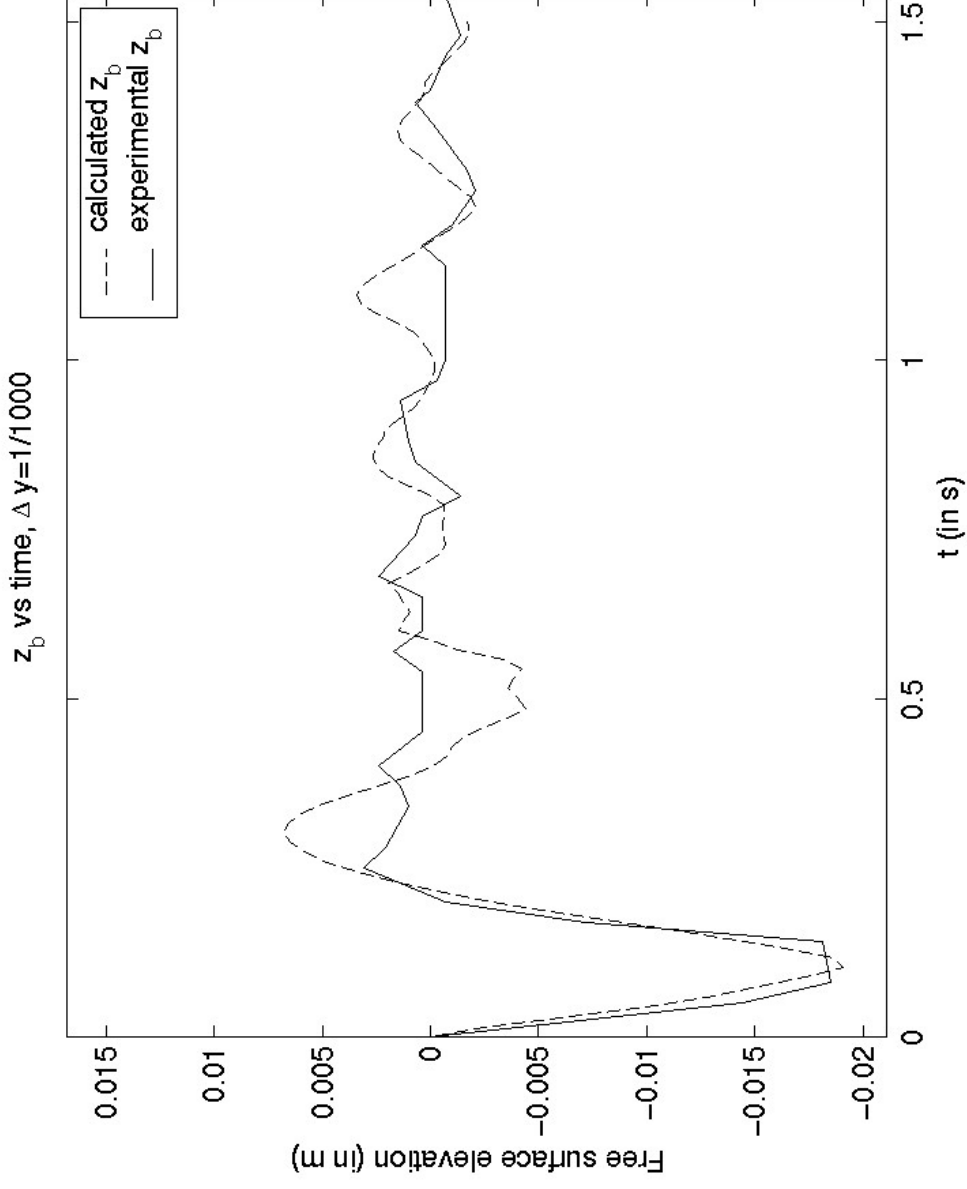
$$g = 9.81 \text{ m.s}^{-2}$$

mesh size : 150×75

Numerical Results : Sloshing in a 2D wedge high Froude number, high Bond number

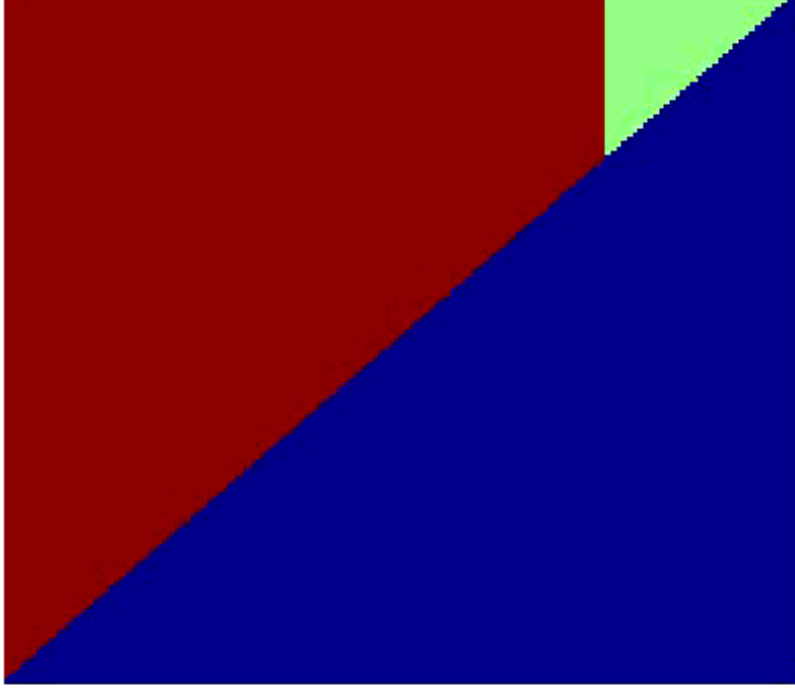


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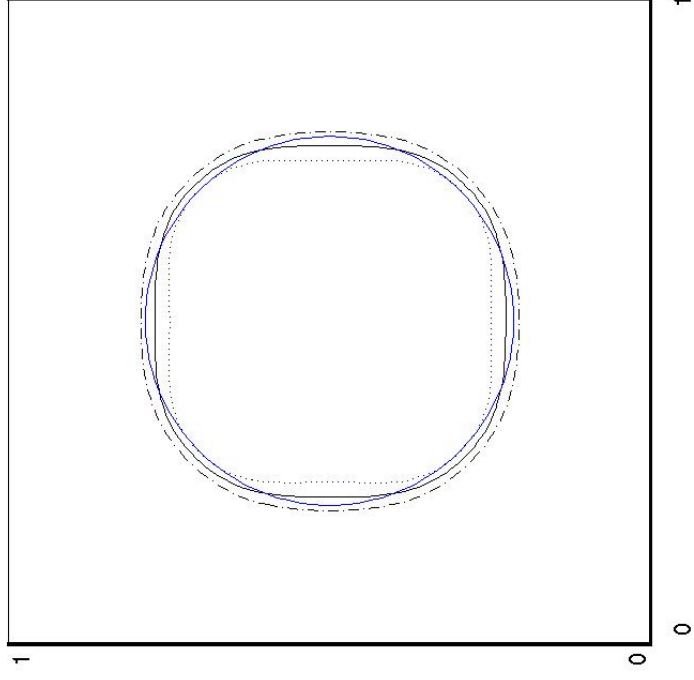
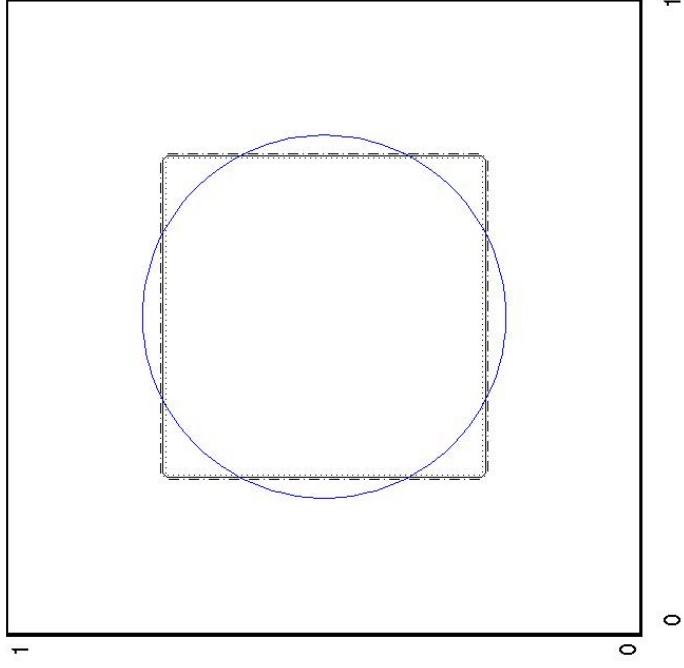


Physically Relevant Quantities

- Total gas volume : $V_g = \int_{\Omega} \alpha \, dV$
- Energies : $F_{\text{tot}} = \underbrace{\int_{\Omega} F \, dV}_{\text{pressure part of the free energy (} F_p \text{)}} + \underbrace{\int_{\Omega} \sigma \|\nabla \alpha\| \, dV}_{\text{remaining part of the free energy: capillary energy (} F_{\text{ts}} \text{)}} + \text{kinetic energy (} F_{\text{ec}} \text{)}$

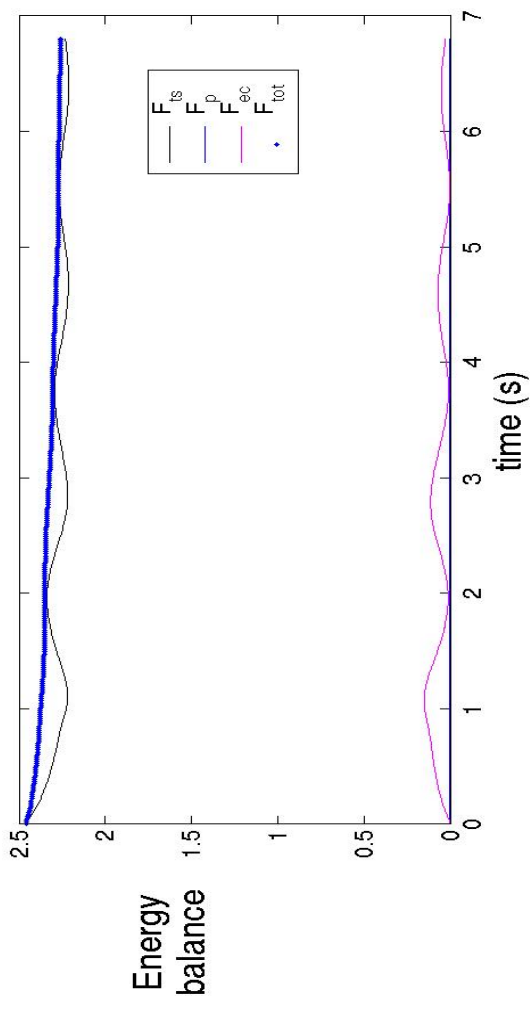
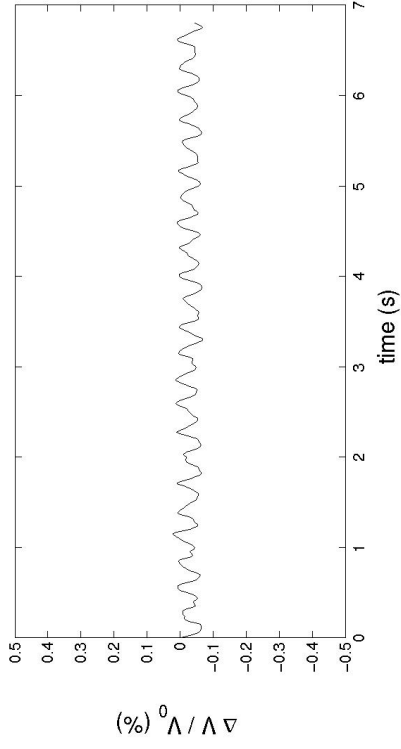
This total energy F_{tot} is decreasing for the relaxation model
(up to a slight modification of the pressure closure law,
current work with D. Jamet, CEA)

Numerical Results : square to circular bubble



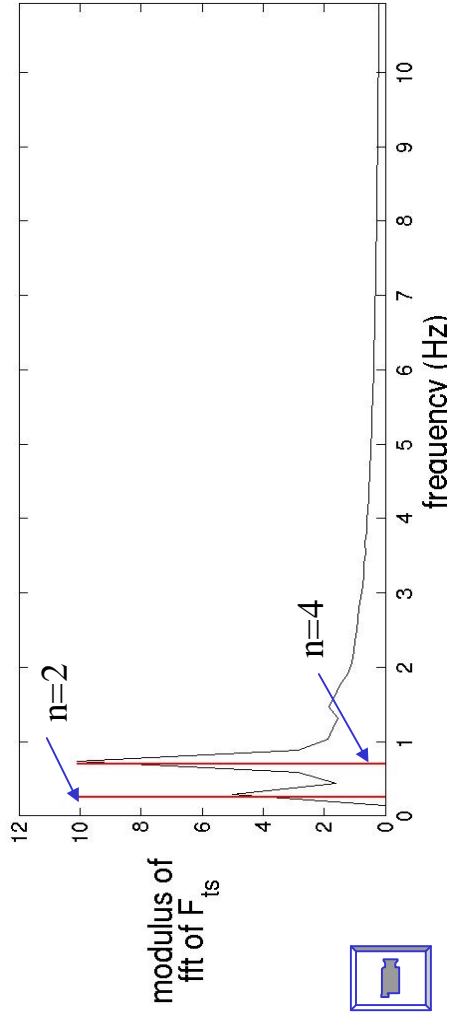
mesh size : 80x80

Numerical Results : square to circular bubble energy balance



Bubble oscillations in a inviscid fluid (Lamb, 1932), deformation modes frequencies :

$$f_n = \frac{1}{\pi} \sqrt{(n+1)(n-1)(n+2)} \frac{\sigma}{\rho_l R^3}$$



Conclusions and Future Developments

- Model and numerical method efficient and accurate for sloshing effects at high Bond number :
 - no numerical scheme required for the gas volume fraction
 - numerical scheme with very low diffusivity compared to similar approaches \Rightarrow low damping of the interface oscillations
 - possible extension of the Riemann solver to more complex EOS (local linearization)
- Capillary forces : validation in progress
- Free energy balance with surface tension effect
- Introduction of viscous and thermal effects
($p(\rho, T)$, conduction, cavitation, evaporation)