

Homework N° 1

The finite element method for a mixed problem

The Stokes problem in \mathbb{R}^d

We consider an open bounded domain $\Omega \subset \mathbb{R}^d$ ($d = 2, 3$) and we denote $\partial\Omega$ its boundary, supposed sufficiently smooth. We first introduce the functional spaces :

$$L_0^2(\Omega) = \left\{ q \in L^2(\Omega), \int_{\Omega} q \, dx = 0 \right\},$$

$$H_{div}^1(\Omega)^d = \left\{ v \in H_0^1(\Omega)^d, \operatorname{div} v = 0 \text{ in } \Omega \right\}.$$

and we provide the following result as a corollary of DeRham theorem :

Corollary 1 *Suppose $f \in H^{-1}(\Omega)^d$ is such that $\langle f, v \rangle = 0$ for all $v \in H_{div}^1(\Omega)^d$. Then, there exists $p \in L^2(\Omega)$ such that $f = \nabla p$. Furthermore, if Ω is a connected set, then p is uniquely defined up to an additive constant and we have the following estimate :*

$$\|p\|_{L^2(\Omega)} \leq C \|f\|_{H^{-1}(\Omega)}.$$

Part I : Variational formulation

We investigate the Stokes problem describing the behavior of an incompressible viscous flow confined in Ω :

Given $f \in L^2(\Omega)^d$ and $\nu \in \mathbb{R}_+^*$, find $u \in H^1(\Omega)^d$ and $p \in L^2(\Omega)$ such that :

$$(\mathcal{S}) \begin{cases} -\nu \Delta u + \nabla p = f, & \text{in } \Omega \\ \operatorname{div} u = 0, & \text{in } \Omega \\ u = 0, & \text{on } \partial\Omega \end{cases} \quad (1)$$

The unknowns are the velocity components in u and the pressure p . Notice that p is only known via its gradient, so it will be defined up to a constant, the latter being fixed by the condition $p \in L_0^2(\Omega)$.

1. Show that the problem (1) is equivalent to the following problem :

Find $(u, p) \in (H_0^1(\Omega)^d, L_0^2(\Omega))$ such that :

$$\begin{cases} \nu \int_{\Omega} \nabla u : \nabla v \, dx - \int_{\Omega} p \operatorname{div} v \, dx = \int_{\Omega} f \cdot v \, dx, & \forall v \in H_0^1(\Omega)^d \\ \operatorname{div} u = 0 & \text{in } \Omega. \end{cases} \quad (2)$$

2. We introduce the following formulation :

Find $u \in H_{div}^1(\Omega)^d$ such that :

$$\nu \int_{\Omega} \nabla u \cdot \nabla v \, dx = \int_{\Omega} f \cdot v \, dx, \quad \forall v \in H_{div}^1(\Omega)^d. \quad (3)$$

- (a) Show that there exists a unique solution u to the problem (3), that depends continuously on the right-hand side term f .
- (b) Deduce from Corollary 1 that there exists a unique $p \in L_0^2(\Omega)$ such that (u, p) is the unique solution of the problem (2), where u is the solution of problem (3). Show that (u, p) depends continuously on f .

Part II : Numerical approximation

We consider an abstract functional context for the Stokes problem.

Let X and M be two Hilbert spaces with their associated norms $\|\cdot\|_X$ and $\|\cdot\|_M$. We introduce two continuous bilinear forms, a defined on $X \times X$ and b defined on $X \times M$ such that the Stokes problem (1) reads :

Given $f \in X'$, find $(u, p) \in X \times M$ such that :

$$(\mathcal{S}) \begin{cases} a(u, v) + b(v, p) = f(v), & \forall v \in X \\ b(u, q) = 0, & \forall q \in M. \end{cases} \quad (4)$$

1. Identify the two bilinear forms a and b corresponding to the Stokes problem (1).
2. Show that the linear mapping $Au : v \mapsto a(u, v)$ is an element of X' and that $A \in \mathcal{L}(X, X')$. Show that the linear mapping $Bu : q \mapsto b(u, q)$ is an element of M' and that $B \in \mathcal{L}(X, M')$.
3. We introduce the space :

$$V = \{v \in X, b(v, q) = 0, \forall q \in M\} = \text{Ker}(B),$$

and we consider the problem :

Find $u \in V$ such that :

$$(\mathcal{P}) \quad a(u, v) = f(v), \quad \text{for all } v \in V. \quad (5)$$

Under what condition(s) the problem (4) above has a unique solution $(u, p) \in X \times M$ such that u is solution of problem (5) ?

Approximation of (\mathcal{S}) .

Let h denotes a discretization parameter. Let $X_h \subset X$ and $M_h \subset M$ be two finite dimensional subspaces. We introduce the following approximation problems :

Find $(u_h, p_h) \in X_h \times M_h$ such that

$$(\mathcal{S}_h) \begin{cases} a(u_h, v_h) + b(v_h, p_h) = f(v_h), & \forall v_h \in X_h \\ b(u_h, q_h) = 0, & \forall q_h \in M_h. \end{cases} \quad (6)$$

Find $u_h \in V_h$ such that :

$$(\mathcal{P}_h) \quad a(u_h, v_h) = f(v_h), \quad \forall v_h \in V_h \quad (7)$$

where

$$V_h = \{v_h \in X_h, b(v_h, q_h) = 0, \forall q_h \in M_h\}.$$

Notice that there is generally no relation between V and V_h ($V_h \not\subset V$).

4. Show that if a is V -elliptic and if the following discrete *inf-sup* condition (LBB condition)

$$\exists \beta_h > 0, \quad \inf_{q_h \in M_h} \sup_{v_h \in X_h} \frac{b(v_h, q_h)}{\|v_h\|_X \|q_h\|_M} \geq \beta_h,$$

is satisfied then the problem (\mathcal{S}_h) has a unique solution $(u_h, p_h) \in X_h \times M_h$ where u_h is the solution of the problem (\mathcal{P}_h) .

5. Here, we assume the two formulations are equivalent. Show that for all $v_h \in V_h, q_h \in M_h$:

$$a(u_h - v_h, u_h - v_h) = a(u - v_h, u_h - v_h) - \langle p - q_h, \operatorname{div}(u_h - v_h) \rangle_{L^2(\Omega)}$$

6. Deduce an estimate of $\|u_h - v_h\|_X$ and that we have :

$$\|u - u_h\|_X \leq C \left(\inf_{v_h \in V_h} \|u - v_h\|_X + \inf_{q_h \in M_h} \|p - q_h\|_M \right).$$

On what parameter depends the constant C ?

7. Show that if the *inf-sup* condition above is satisfied, then :

$$\|p_h - q_h\|_M \leq C_1 \|q_h - p\|_M + C_2 \|u - u_h\|_X, \quad \forall q_h \in M_h.$$

8. Deduce the estimate :

$$\|u - u_h\|_X + \|p - p_h\|_M \leq C_1 \inf_{v_h \in V_h} \|u - v_h\|_X + C_2 \inf_{q_h \in M_h} \|p - q_h\|_M.$$

Compute the constants C_1 and C_2 .

Part III : *Finite element approximation*

We consider the Stokes problem (1) posed in \mathbb{R}^2 . The domain $\Omega =]0, 1[^2$ is supposed to be covered by a mesh T_h , where the parameter h denotes the grain of the discretization : $h = \max_{K \in T_h} \operatorname{diam}(K)$.

We introduce the following approximation spaces :

$$\begin{aligned} X_h &= \{v_h \in C^0(\bar{\Omega})^2, v_h|_K \in \mathbb{P}_1, \forall K \in T_h \text{ and } v_h|_{\partial\Omega} = 0\} \\ M_h &= \{q_h \in L^2(\Omega), q_h|_K \in \mathbb{P}_0, \forall K \in T_h \text{ and } \int_{\Omega} q_h dx = 0\}. \end{aligned}$$

9. Show that $X_h \subset X = H_0^1(\Omega)^2$, and $M_h \subset M = L_0^2(\Omega)$.

10. Show that these approximation spaces do not satisfy the discrete *inf-sup* condition for the bilinear form b of the Stokes problem. To this end, show that there exists $p_h \neq 0 \in M_h$ such that $\int_{\Omega} p_h \operatorname{div} v_h dx = 0$, for all $v_h \in X_h$.
11. To circumvent this problem, we introduce another approximation space, between \mathbb{P}_1^2 and \mathbb{P}_2^2 . We consider the polynomial space :

$$P(K) = (\mathbb{P}_1 \oplus \operatorname{Span}\{p_1, p_2, p_3\})^2$$

where

$$p_1 = n_1 \lambda_2 \lambda_3, \quad p_2 = n_2 \lambda_3 \lambda_1, \quad p_3 = n_3 \lambda_1 \lambda_2,$$

and n_i denotes the outer normal to edge e_i in triangle K and the λ_i are the barycentric coordinates of the mid-points of the edges. The degrees of freedom associated with $P(K)$ are defined as :

$$\Sigma = \{v \rightarrow v(a_i), \quad 1 \leq i \leq 3, \quad v \rightarrow \int_{e_i} v \cdot n_i dx, \quad 1 \leq i \leq 3\},$$

where $(a_i)_{1 \leq i \leq 3}$ denote the vertices of K .

- (a) Check that the $(p_i)_{1 \leq i \leq 3}$ are linearly independent and that $P(K)$ is a direct sum.
- (b) Show that $(K, P(K), \Sigma)$ is a finite element and determine the shape functions associated with the vertices a_i of K and with the other degrees of freedom.
- (c) Define the interpolation operator Π_K for the finite element $(K, P(K), \Sigma)$. Show that

$$v \in P(K) \Rightarrow \Pi_K v = v.$$

- (d) We keep the space M_h and we consider now a new approximation space :

$$X_h = \{v_h \in C^0(\bar{\Omega})^2, \quad v_h|_K \in P(K), \quad \forall K \in T_h \text{ and } v_h|_{\partial\Omega} = 0\} \subset X = H_0^1(\Omega)^2.$$

Suppose the discrete *inf-sup* condition is satisfied for (M_h, X_h) with respect to the bilinear form b of the Stokes problem. Provide an estimate of :

$$\inf_{w_h \in X_h} |v - w_h|_{H^1(\Omega)}, \quad \text{where } |u|_{H^1(\Omega)} = \left(\int_{\Omega} (\nabla u)^2 \right)^{1/2}$$

for $v \in X \cap H^2(\Omega)^2$, when the mesh T_h is uniform of size h .

- (e) We consider the orthogonal projection operator P_K from $L^2(K)$ onto \mathbb{P}_0 :

$$\int_K (P_K q - q) dx = 0, \quad \text{with } P_K q \in \mathbb{P}_0 \quad \text{and } q \in L^2(K).$$

Prove that if $q \in H^1(K)$ then

$$\|q - P_K q\|_{L^2(K)} \leq Ch |q|_{H^1(K)}$$

where C is independent of K . Let $P_h : M \rightarrow M_h$ be the operator such that :

$$P_h q|_K = P_K q.$$

Verify that $P_h q \in M_h$ if $q \in M$. Deduce from the previous question that :

$$\inf_{q_h \in M_h} \|p - q_h\|_{L^2(\Omega)} \leq Ch |p|_{H^1(\Omega)}, \quad \text{if } p \in H^1(\Omega).$$

- (f) What is the purpose of having estimates on $\inf_{w_h \in X_h} |v - w_h|_{H^1(\Omega)}$ and $\inf_{q_h \in M_h} \|p - q_h\|_{L^2(\Omega)}$?